



the ultra-acoustic equipment (with frequency of 28 kHz and the power of 400W) [4].

The high complexity of the electrical discharge manufacturing process and the ultra-acoustic process, due to a great number of factors, rise the manufacturing cell adjustments in comparison with an objective function, such as the manufacturing productivity. Among other, this parameter is function of the tool electrode speed which can be determined with the following relation:

$$dV_s/dI_m \tag{1}$$

in comparison with time one obtain:

$$dV_s/dt \text{ and } dI_m/dt. \tag{2}$$

but these elements are hard to control and even hard to express (mathematical), that is why one consider other elements of the manufacturing process, taking into account their extreme values between which the manufacturing process parameters must varies. In this way the manufacturing productivity can be evaluated based on indirect criteria such as the ratio between effective impulse number and fictitious impulse number or the delay from the launching of the potential impulse and the appearing of the current in working space. In this case, one considers optimum working conditions, for a given situation, when the number of fictitious impulse number is minimum.

The distance between electrodes in the idle running impulse case must be shorten and in the short circuit case must be increased. The manufacturing optimum regime must be situated between these two extreme situations and the number of the working impulse must have maximum value from the total number of impulses.

In the case of the potential impulse one exist an certain maximum value of the potential which must not be exceed and for the current impulse a certain time which determine the impulse size. The optimum working regime must be situated among above mentioned limits. In Fig. 2 on distinguish: 1 and 2 blocks for the current impulse initiation; 3 – logical circuit; 4 and 5 – blocks of the potential impulse initiation; 6 – fictitious impulse detector; 7 – workmanship element; 8 – automat potentiometer; 9 – feed self-regulator.

In the case of full potential signal one have only current signal and this means short circuit situation and the logical circuit 3 will send a signal of removing the electrodes. In the case of null current signal one have just potential signal. This means that one have a great distance

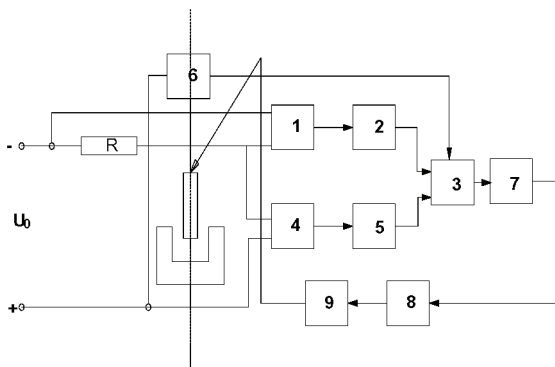


Fig. 2. Block diagram of commands.

between electrodes, logical circuit 3 will sent a signal for approaching the electrodes.

The optimum working regime is obtained when it exist both potential and current signals. In this period one the fictitious impulse detector 6 is present by approaching the electrodes.

In order to utilize the value of the command and optimization scheme of the EDMUS manufacturing process (Fig. 3) is useful to present the relation between the EDMUS working cycle possible impulse types. In Fig. 3 one distinguish the CCAA – command head of the vertical feed; GOUAS – ultra-acoustic oscillation generator; GI – electrical discharge impulse generator; BC – command block

$$F_i = f_p + f_M + f_G + f_{SC} + f_o, \tag{3}$$

where:  $f_i$  – impulse frequency;  $f_p$  – sampling impulse frequency;  $f_M$  – crumbling impulse frequency;  $f_G$  – fictitious impulse frequency in working zone (ML);  $f_{SC}$  – short circuit impulse frequency;  $f_o$  – idle running impulse frequency.

The sampling impulse frequency has a primary sampling impulse component –  $f_{PP}$  and  $a$  a sampling and crumbling impulse component –  $f_{PM}$  with a sampling efficiency  $\eta$

$$F_p = f_{PP} + \eta f_{PM}, \tag{4}$$

$f_M$  will be:

$$F_M = f_{SM} + (1 - \eta) f_{PM}, \tag{5}$$

where  $f_{SM}$  is the crumbling joint impulse at the  $f_{SM}$  frequency of secondary impulses of pure crumbling.

The first machining trial with the new equipment is encouraging. One find a meaningful decreasing of the

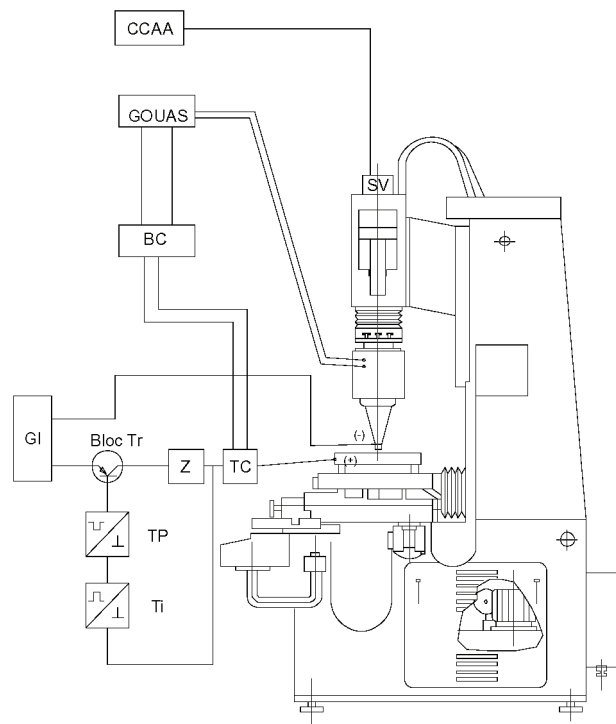


Fig. 3. Equipment for hybrid machining.

machining time for the bore with diameter of 5 mm and plate thickness of 5 mm.

These two machining types combination (Electrical Discharge Machining with Ultrasonic Assistance-EDMUS) had a series of consequences, most of them favorable, upon the machining technologies, working parameters, the quality of the machined surface, in a word, upon the technical and economical performance. The ultra-acoustic oscillation is overlap on the electrical discharge process which leads to benefit effects in machining through the cavity phenomenon. Thus on improve the washing conditions in working zone and one accelerated the matter sampling process from the erosion crater. These elements are decisive in small dimensions boring and cross line network [5].

The tool-electrode or work-piece ultra-acoustic oscillation movement accelerated the elimination of the micro-granular detached in the machining process and increase the pumping phenomenon; one eliminated the contaminated dielectric and the clean dielectric come in fast, facilitating a new series of discharges, thus increasing their efficiency and the sampling speed.

The second benefit in the ultra-acoustic discharge machining is bounded to the machined matter structural modification. The alternate movement of the tool-electrode with high frequency given by the ultra-acoustic oscillation amplifies the turbulence and cavity phenomena which have as result an efficient ejection of the electrical discharge machining products from the working zone.

The machining parameters were watching with the help of an oscilloscope, PICOSCOP type (England) using a scheme presented in Fig. 4.

In Figs. 5 and 6 one presents two of the oscillograms showing the evolution of the electrical discharges in working zone, using an ED classical process and the new process called EDMUS.

The hybrid manufacturing process, named EDMUS (Electro Discharge Machining and Ultrasonic Machining) bring an uniformity of the electrical discharges by modifying the discharge conditions between the electrodes. One can observe from Fig. 5, after a discharge zone through an simple ED process which include both A1 and A2 zones (the starting of the discharge is not started), a zone where for an interval of 358 microseconds one determine a discharge frequency of 27 discharge per

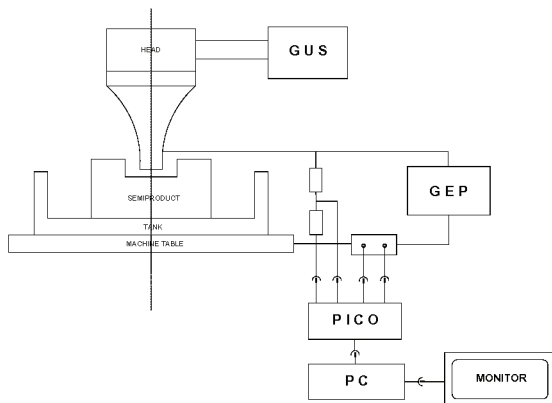


Fig. 4. Equipment for measuring of technological parameter.

second in which all discharges are with material removal. If one define an filling coefficient as the ratio between the removal discharges  $f_p$  and the total number of discharges  $f_j$ , one can determine that one have maximum value on this interval and in command scheme (Fig. 2) one have maximum productivity.

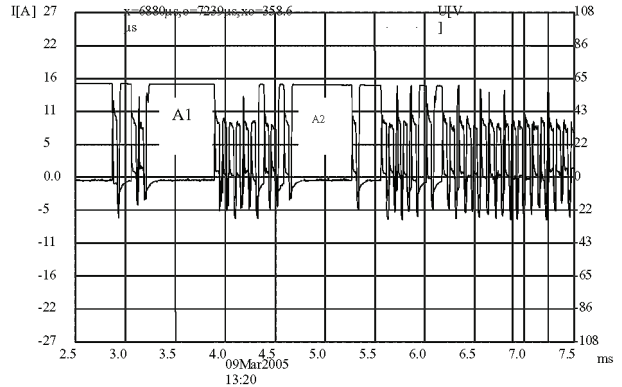


Fig. 5. Series of discharges – classic procedure ED (first level of power).

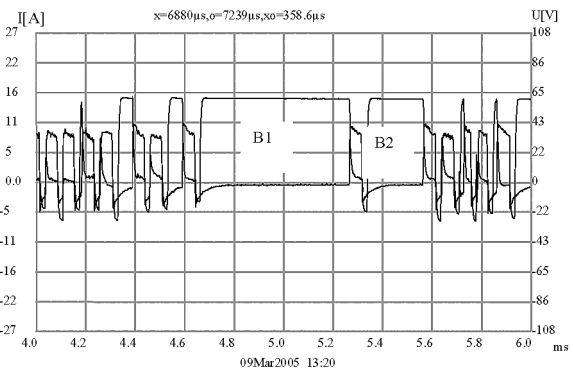


Fig. 6. Series of discharges-EDMUS procedure.

In Fig. 6 one considers an EDM type discharging zone where B1 and B2 zones are discharges without starting. For these one do not establish optimum conditions for brake off the space between the electrodes and the machine tool is idle running. The productivity is reduced and the electrical energy consumption is high. As soon as the EDMUS start one determine, after 5,6 microseconds, a calm down of the electrical discharge between the electrodes, maintaining the value of the starting potential in time, and a constant discharge current. Also one has a positive effect of the discharge energy which assures a uniform quality of the manufactured surface.

### 3. CONCLUSION

The attempt of association of two unconventional machining processes – electrical discharge machining and ultra acoustic oscillation machining – could be materialized using new machining equipment which is called hybrid machining technology. The equipment are relatively simple to handle and can be used separately or together. These two classical machining technologies do not give birth to a new unconventional technology. Their

separate action could be easily emphasized but working together one could observe an improving of the technological performance through much better working conditions given by those two processes, one for the other. The present paper aim to present such an achievement obtained in the Fine Mechanics Department, “Gh. Asachi” Technical University, Iași, Romania.

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